

Notes about the Quaternions, and the Subfield test

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Hi kids! This document is really just about two different and somewhat unrelated aspects of Section 6.3: the quaternions, and the subfield test. Corey asked me to please write a handout for all of you since he's so busy with everything else. After all, I'm one of his mentors, so I decided it might be fun. ROCK ON!

1 The Subfield Test.

We give a good proof of this test, Corey really isn't that happy with how it went in class.

Theorem. (Subfield Test) Suppose $\emptyset \neq S \subseteq F$. Then S is a subfield of F if and only if for all $a, b \in S$, we have (1) $a - b \in S$, and (2) for $b \neq 0$, we have $ab^{-1} \in S$.

Proof. It's more or less obvious that if S is a subfield of F , then (1) (S is a subring) and (2) (inverses and products are closed in fields) hold. So conversely, suppose (1) and (2) hold. We have to show S is a subring of F , S is commutative, $1 \in S$, and that every nonzero element of S has a multiplicative inverse. First, we choose $a = b$ in (2) to conclude that $aa^{-1} = 1 \in S$. Now we use $a = 1 \in S$, and any $0 \neq b \in S$ to conclude $1 \cdot b^{-1} = b^{-1} \in S$. Now we use $a \in S$, and $0 \neq b^{-1} \in S$ to conclude $a(b^{-1})^{-1} = ab \in S$. If $b = 0$, then it is clear that $ab = 0 \in S$, since, by (1) with $a = b$, we have $a - b = 0 \in S$. By the subring test, S is a subring of F . Since $S \subset F$, a commutative ring, all elements of S commute. So S is a subfield of F .

2 Hamilton's Quaternions.

We discussed this ring in detail in class. Corey vowed to give you all a better proof as to why every nonzero element has an inverse. It will follow that there are no zero divisors in \mathbb{H} . I refer you to Example 6.3.20 on page 206 for a definition of \mathbb{H} . So here it goes. Define

$$\Theta := \{x_1i + x_2j + x_3k \mid x_i \in \mathbb{R}\}.$$

Now define the function $\|\cdot\| : \mathbb{H} \rightarrow \mathbb{R}$ as $\|x_0 + x_1i + x_2j + x_3k\| = \sqrt{\sum x_i^2}$. It is clear that $\|\alpha\| = 0$ if and only if $\alpha = 0$. Now suppose $\alpha = x_0 + \theta \neq 0$. We claim that

$$\alpha^{-1} = \frac{x_0 - \theta}{\|\alpha\|^2}.$$

We check this by first supposing that $\theta = x_1i + x_2j + x_3k$, and notice two facts before we begin. For any $x_0 \in \mathbb{R}$, we have

$$x_0\theta = x_0(x_1i + x_2j + x_3k) = x_0x_1i + x_0x_2j + x_0x_3k = x_1ix_0 + x_2jx_0 + x_3kx_0 = \theta x_0.$$

Namely, real scalars commute with Θ . Also, we compute

$$\begin{aligned} \theta^2 &= (x_1i + x_2j + x_3k)(x_1i + x_2j + x_3k) \\ &= -x_1^2 + x_1x_2ij + x_1x_3ik + x_2x_1ji - x_2^2 + x_2x_3jk + x_1x_3ki + x_3x_2kj - x_3^2 \\ &= -x_1^2 - x_2^2 - x_3^2 + x_1x_2k - x_1x_3j - x_2x_1k + x_2x_3i + x_1x_3j - x_3x_2i \\ &= -x_1^2 - x_2^2 - x_3^2. \end{aligned}$$

Now we are ready to prove our claim. Notice that

$$\begin{aligned} \alpha\alpha^{-1} &= (x_0 + \theta) \frac{(x_0 - \theta)}{\|\alpha\|^2} \\ &= \frac{1}{\|\alpha\|^2} (x_0 + \theta)(x_0 - \theta) \\ &= \frac{1}{\|\alpha\|^2} (x_0^2 - x_0\theta + \theta x_0 - \theta^2) \\ &= \frac{1}{\|\alpha\|^2} (x_0^2 - \theta^2) \\ &= \frac{1}{\|\alpha\|^2} (x_0^2 + x_1^2 + x_2^2 + x_3^2) \\ &= 1. \end{aligned}$$

ROCK ON!!!